

# Claims

[c1] What is claimed is:

1.A method for detecting early fires in a predetermined area, the method comprising:

- (a) capturing a plurality of images of the predetermined area during an interval for generating a plurality of difference frames;
- (b) detecting a number of pixels that have fire characteristics in each difference frame; and
- (c) if the result of step (b) indicates that a flame in the predetermined area substantially increases during the interval, outputting an early fire alarm.

[c2] 2.The method of claim 1 wherein step (b) includes: determining if each pixel of each difference frame complies with the following rules:

$R > R_t$ ;

$R \geq G > B$ ; and

$S \geq ((255 - R) * S_t / R_t)$ ;

wherein R is a value of a red component of the pixel,  $R_t$  is a threshold of the red component, G is a value of a green component of the pixel, B is a value of a blue component of the pixel, S is saturation of the pixel,  $S_t$  is

a threshold of saturation; and  
if a pixel complies with the above rules, adjusting the number of pixels that have fire characteristics of the difference frame.

- [c3] 3.The method of claim 2 wherein when the value of the red component of a pixel is  $R_t$ , the saturation of the pixel is  $S_t$ .
- [c4] 4.The method of claim 1 wherein in step (c), if the result of step (b) indicates that a ratio of spreading flame in the predetermined area is over a threshold of spreading flame during the interval, then outputting the early fire alarm.
- [c5] 5.The method of claim 1 wherein step (a) including:  
comparing two images captured for generating a difference of the two images; and  
removing noise from the difference for generating a difference frame.
- [c6] 6.A method for detecting a number of pixels that have fire characteristics in a difference frame, the method comprising:  
determining if each pixel of the difference frame complies with the following rules:  
 $R > R_t$ ;

$R \geq G > B$ ; and

$S \geq ((255 - R) * St / Rt)$ ;

wherein R is a value of a red component of the pixel,  $R_t$  is a threshold of the red component, G is a value of a green component of the pixel, B is a value of a blue component of the pixel, S is saturation of the pixel,  $S_t$  is a threshold of saturation; and

if a pixel complies with the above rules, adjusting the number of pixels that have fire characteristics of the difference frame.

[c7] 7.The method of claim 6 wherein when the value of the red component of a pixel is  $R_t$ , the saturation of the pixel is  $S_t$ .

[c8] 8.The method of claim 6 wherein a video detecting system captures images in a predetermined area and the difference frame is generated by removing noise of a difference of two images captured by the video detecting system.

[c9] 9.A video detecting system comprising:  
an image capturing device for capturing images;  
a logic unit for performing the following steps:  
(a) controlling the image capturing device to capture a plurality of images of a predetermined area during an interval for generating a plurality of difference frames;

(b) detecting a number of pixels that have fire characteristics in each difference frame; and  
(c) if the result of step (b) indicates that a flame in the predetermined area substantially increases during the interval, outputting an early fire alarm.

[c10] 10. The video detecting system of claim 9 wherein step (b) performed by the logic unit includes:  
determining if each pixel of the difference frame complies with the following rules:

$R > R_t$ ;

$R \geq G > B$ ; and

$S \geq ((255 - R) * S_t / R_t)$ ;

wherein  $R$  is a value of a red component of the pixel,  $R_t$  is a threshold of the red component,  $G$  is a value of a green component of the pixel,  $B$  is a value of a blue component of the pixel,  $S$  is saturation of the pixel,  $S_t$  is a threshold of saturation; and  
if a pixel complies with the above rules, adjusting the number of pixels that have fire characteristics of the difference frame.

[c11] 11. The video detecting system of claim 10 wherein when the value of the red component of a pixel is  $R_t$ , the saturation of the pixel is  $S_t$ .

[c12] 12. The video detecting system of claim 9 wherein if the

result of step (b) indicates that a ratio of spreading flame in the predetermined area is over a threshold of spreading flame during the interval, the logic unit outputs the early fire alarm.

[c13] 13. The video detecting system of claim 9 wherein step (a) performed by the logic unit includes:  
comparing two images captured for generating a difference of the two images; and  
removing noise from the difference for generating a difference frame.

[c14] 14. The video detecting system of claim 9 wherein the logic unit is a logic circuit.

[c15] 15. The video detecting system of claim 9 wherein the logic unit is a program code.

[c16] 16. A video detecting system comprising:  
an image capturing device for capturing images;  
a logic unit for performing the following steps:  
(a) determining if pixels of difference frames complies with the following rules, the difference frames generated from images captured by the video detecting system:  
 $R > R_t$ ;  
 $R \geq G > B$ ; and  
 $S \geq ((255 - R) * S_t / R_t)$ ;

wherein  $R$  is a value of a red component of the pixel,  $R_t$  is a threshold of the red component,  $G$  is a value of a green component of the pixel,  $B$  is a value of a blue component of the pixel,  $S$  is saturation of the pixel,  $S_t$  is a threshold of saturation; and

(b) if a pixel complies with the above rules, adjusting a number of pixels that have fire characteristics of the difference frame.

[c17] 17.The video detecting system of claim 16 wherein when the value of the red component of a pixel is  $R_t$ , the saturation of the pixel is  $S_t$ .

[c18] 18.The video detecting system of claim 16 wherein step (a) performed by the logic unit includes:  
comparing two images captured for generating a difference of the two images; and  
removing noise from the difference for generating a difference frame.

[c19] 19.The video detecting system of claim 16 wherein the logic unit is a logic circuit.

[c20] 20.The video detecting system of claim 16 wherein the logic unit is a program code.